

PHYS 151

Lecture 04

Ch 04 Motion in Two and Three Dimensions

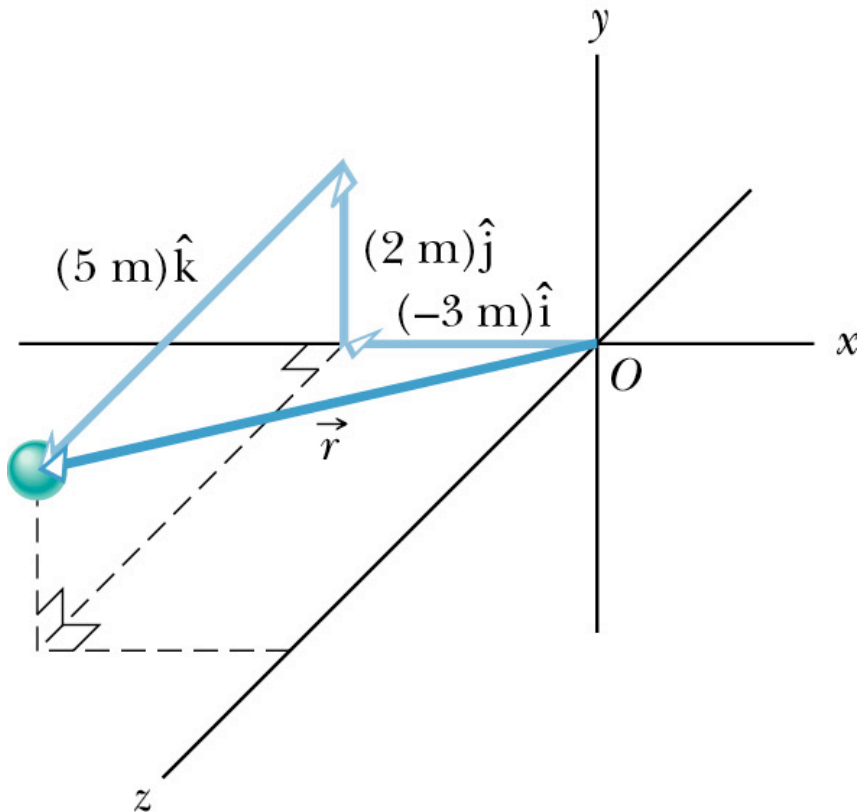
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Position and Displacement

One general way of locating a particle:

position vector

$$\vec{r} = x\hat{i} + y\hat{j} + z\hat{k} \quad \text{ex) } \vec{r} = (-3 \text{ m})\hat{i} + (2 \text{ m})\hat{j} + (5 \text{ m})\hat{k}$$



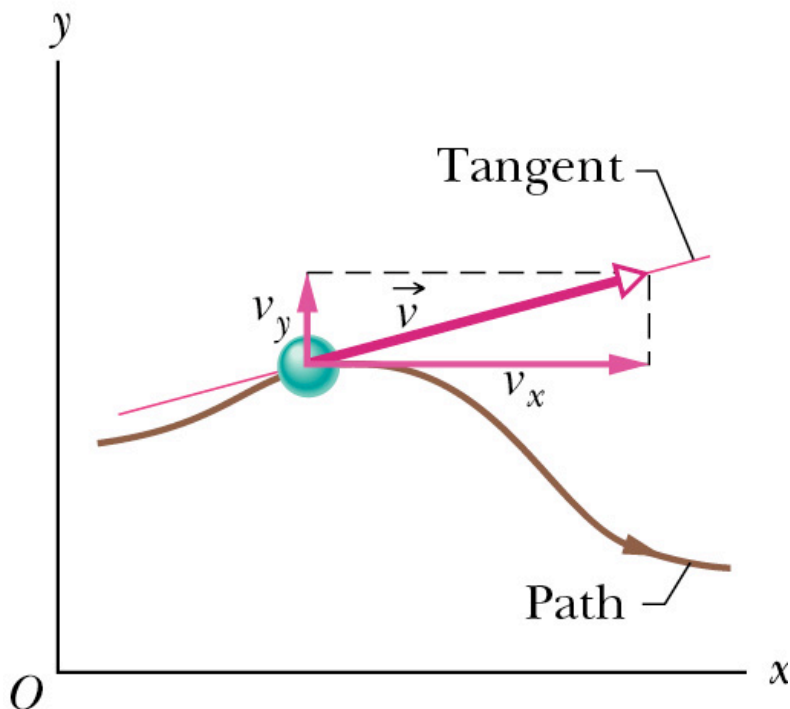
Displacement vector:

$$\begin{aligned} \Delta\vec{r} &= \vec{r}_2 - \vec{r}_1 \\ &= (x_2\hat{i} + y_2\hat{j} + z_2\hat{k}) - (x_1\hat{i} + y_1\hat{j} + z_1\hat{k}) \\ &= (x_2 - x_1)\hat{i} + (y_2 - y_1)\hat{j} + (z_2 - z_1)\hat{k} \\ &= \Delta x\hat{i} + \Delta y\hat{j} + \Delta z\hat{k} \end{aligned}$$

Average and Instantaneous Velocity

Average velocity $\vec{v}_{avg} = \frac{\Delta \vec{r}}{\Delta t} = \frac{\Delta x}{\Delta t} \hat{i} + \frac{\Delta y}{\Delta t} \hat{j} + \frac{\Delta z}{\Delta t} \hat{k}$

Instantaneous velocity $\vec{v} = \frac{d\vec{r}}{dt} = \frac{dx}{dt} \hat{i} + \frac{dy}{dt} \hat{j} + \frac{dz}{dt} \hat{k}$
 $= v_x \hat{i} + v_y \hat{j} + v_z \hat{k}$

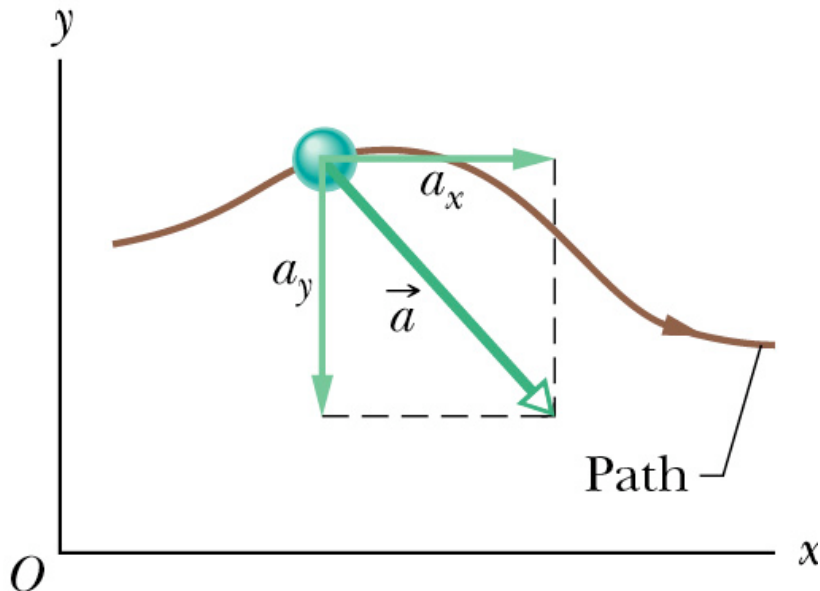


The direction of the velocity is always tangent to the particle's path

Average and Instantaneous Acceleration

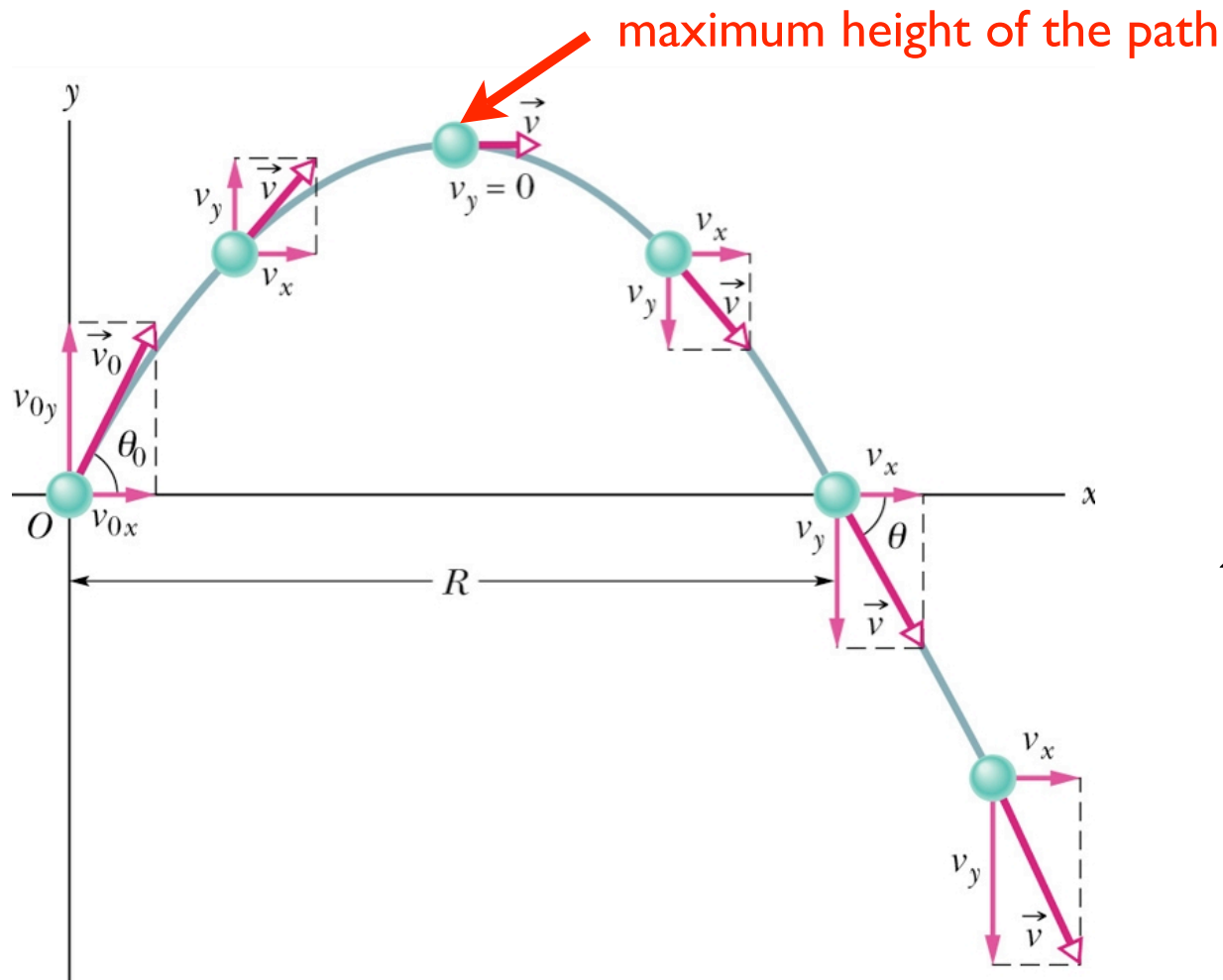
Average acceleration $\vec{a}_{avg} = \frac{\Delta \vec{v}}{\Delta t}$

Instantaneous acceleration $\vec{a} = \frac{d\vec{v}}{dt} = \frac{dv_x}{dt} \hat{i} + \frac{dv_y}{dt} \hat{j} + \frac{dv_z}{dt} \hat{k}$
 $= a_x \hat{i} + a_y \hat{j} + a_z \hat{k}$



Projectile motion

: a particle moves in a vertical plane with some initial velocity but its acceleration is always the free fall acceleration (g) then is called a **projectile motion**



In projectile motion, the **horizontal** motion and the **vertical** motion are **independent** each other

Projectile motion Analyzed

The horizontal motion: no acceleration in x direction

$$\begin{aligned}x - x_0 &= v_{0x}t + \underbrace{\frac{1}{2}a_x t^2}_{=0} \\ &= (v_0 \cos \theta_0)t\end{aligned}$$

The vertical motion: acceleration (-g) in y direction

$$\begin{aligned}y - y_0 &= v_{0y}t + \frac{1}{2}(-g)t^2 \\ &= (v_0 \sin \theta_0)t - \frac{1}{2}gt^2\end{aligned}$$

(Yes, we've learned
these in ch02)


$$v = v_0 + at \quad \rightarrow \quad v_y = v_0 \sin \theta_0 - gt$$

$$v^2 = v_0^2 + 2a(x - x_0) \quad \rightarrow \quad v_y^2 = (v_0 \sin \theta_0)^2 - 2g(y - y_0)$$

Projectile motion : path

Simplicity, we let $x_0=y_0=0$ (starting at the origin of the coordinate system)

$$\begin{aligned}x &= v_0 \cos \theta_0 t \\y &= v_0 \sin \theta_0 t - \frac{1}{2}gt^2\end{aligned}$$

Solve the first equation for t and replace t in the 2nd equation,

$$\begin{aligned}y &= v_0 \sin \theta_0 \frac{x}{v_0 \cos \theta_0} - \frac{1}{2}g \left(\frac{x}{v_0 \cos \theta_0} \right)^2 \\&= (\tan \theta_0)x - \frac{gx^2}{2(v_0 \cos \theta_0)^2}\end{aligned}$$

This is of the form $y = ax + bx^2$, that is the **equation of a parabola** (포물선)

Projectile motion : horizontal range

The horizontal distance that the projectile has traveled when it returns to its initial height: R

$$\text{Let } x - x_0 = R \text{ and } y - y_0 = 0$$

$$R = (v_0 \cos \theta_0)t$$

$$0 = (v_0 \sin \theta_0)t - \frac{1}{2}gt^2$$

From the 2nd equation, we get

$$v_0 \sin \theta_0 = \frac{1}{2}gt$$

With the 1st equation, we eliminate t

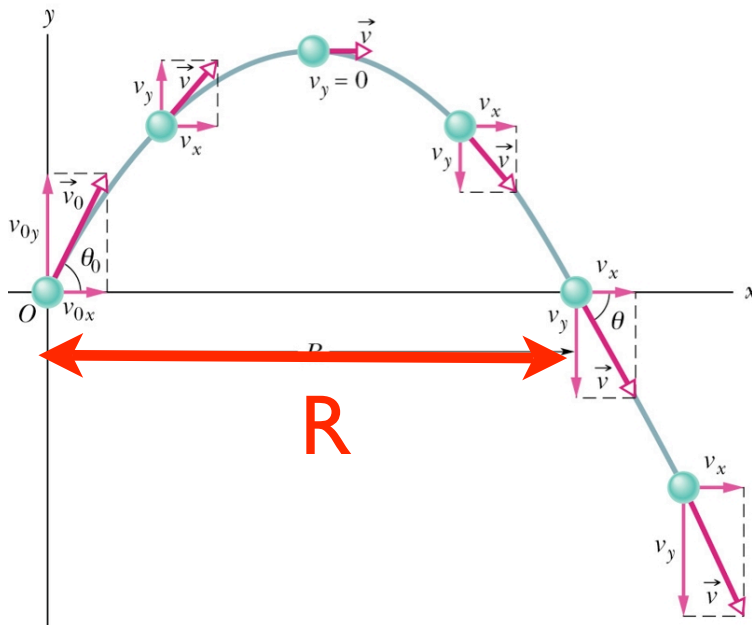
$$v_0 \sin \theta_0 = \frac{1}{2}g \frac{R}{v_0 \cos \theta_0}$$

$$R = \frac{2v_0^2}{g} \sin \theta_0 \cos \theta_0$$

$$= \frac{v_0^2}{g} \sin 2\theta_0$$

$$\sin 2\theta_0 = 2 \sin \theta_0 \cos \theta_0 \longrightarrow$$

is used here



Projectile motion : horizontal range

R has its maximum value when the angle = 45°

(so you should throw baseball with the angle 45° to maximize the distance?)

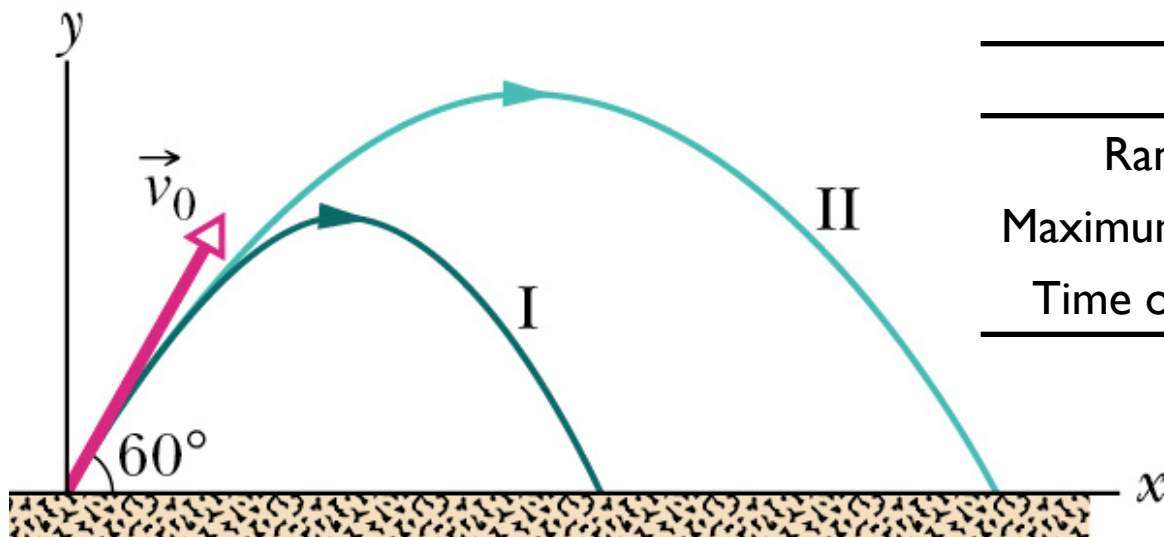
The effects of the air

:The air resists the motion

(angle = 60° , initial speed 44.7 m/s)

I : path with air resistance

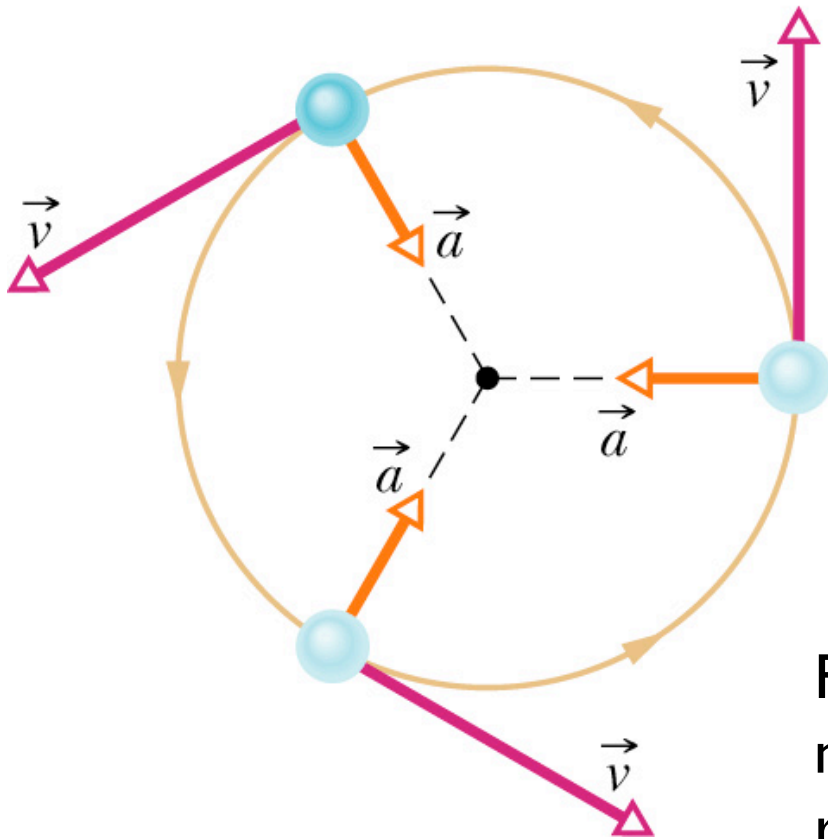
II : path in vacuum



	Path I (air)	Path II (vacuum)
Range	98.5 m	177 m
Maximum height	53.0 m	76.8 m
Time of flight	6.6 s	7.9 s

Uniform circular motion

: if a particle travels around a circle (or a circular arc) at constant (uniform) speed, it is in **uniform circular motion**



speed is constant but $\vec{a} = \frac{d\vec{v}}{dt} \neq 0$
(direction is changing)

\vec{v} is directed tangent to the circle
 \vec{a} is directed radially inward

Uniform circular motion is called **centripetal** (center seeking, 구심성의...) **acceleration**

For uniform circular motion, the following relations hold (r : radius of the circle, T : period of the revolution)

$$a = \frac{v^2}{r}$$
$$T = \frac{2\pi r}{v}$$

Uniform circular motion

From the figure, we get

$$\begin{aligned}\vec{v} &= v_x \hat{i} + v_y \hat{j} = (-v \sin \theta) \hat{i} + (v \cos \theta) \hat{j} \\ &= (-v) \frac{y_p}{r} \hat{i} + v \frac{x_p}{r} \hat{j}\end{aligned}$$

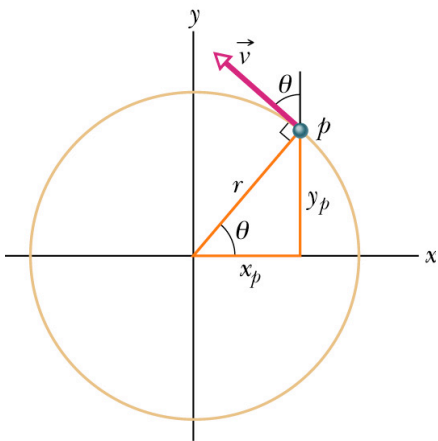
We take the time derivative of the above:

$$\begin{aligned}\vec{a} &= \frac{d\vec{v}}{dt} = \left(-\frac{v}{r} \frac{dy_p}{dt} \right) \hat{i} + \left(\frac{v}{r} \frac{dx_p}{dt} \right) \hat{j} \\ &= \left(-\frac{v}{r} v_y \right) \hat{i} + \left(\frac{v}{r} v_x \right) \hat{j} \\ &= \left(-\frac{v^2}{r} \cos \theta \right) \hat{i} + \left(-\frac{v^2}{r} \sin \theta \right) \hat{j}\end{aligned}$$

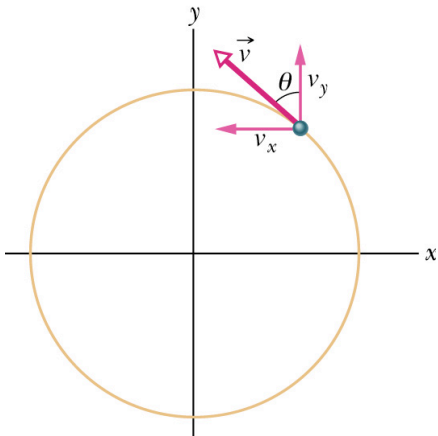
$$a = \sqrt{a_x^2 + a_y^2} = \frac{v^2}{r} \sqrt{\cos^2 \theta + \sin^2 \theta} = \frac{v^2}{r}$$

$$\tan \phi = \frac{a_y}{a_x} = \frac{-(v^2/r) \sin \theta}{-(v^2/r) \cos \theta} = \tan \theta$$

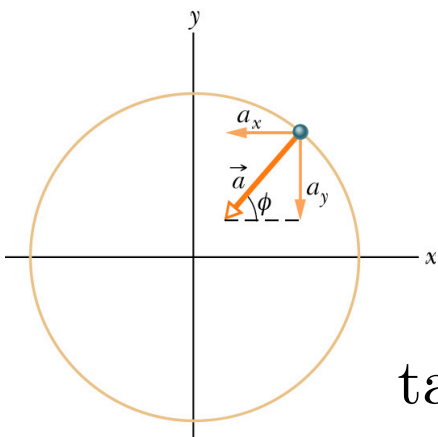
\vec{a} is directed along the radius r , toward the center



(a)

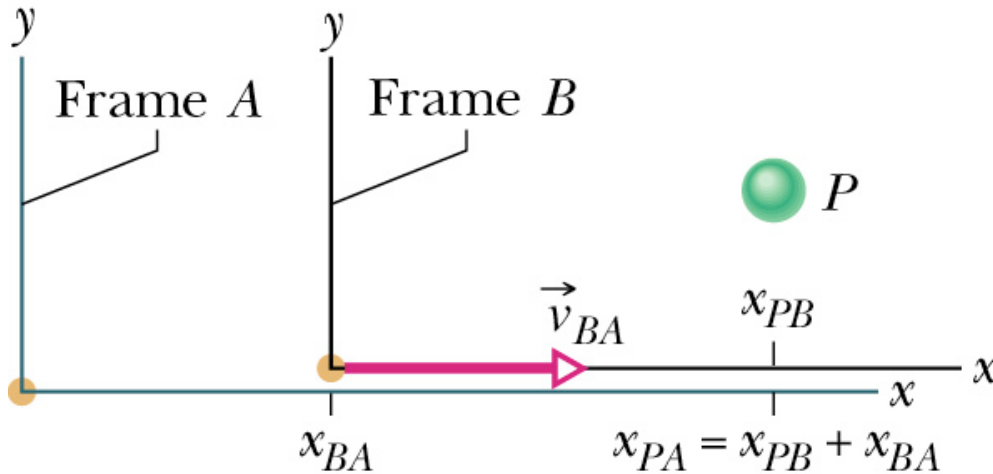


(b)



(c)

Relative Motion in One dimension



The velocity of a particle depends on the reference frame

(we assume a constant speed v_{BA})

$$x_{PA} = x_{PB} + x_{BA}$$

Time derivative of the above gives

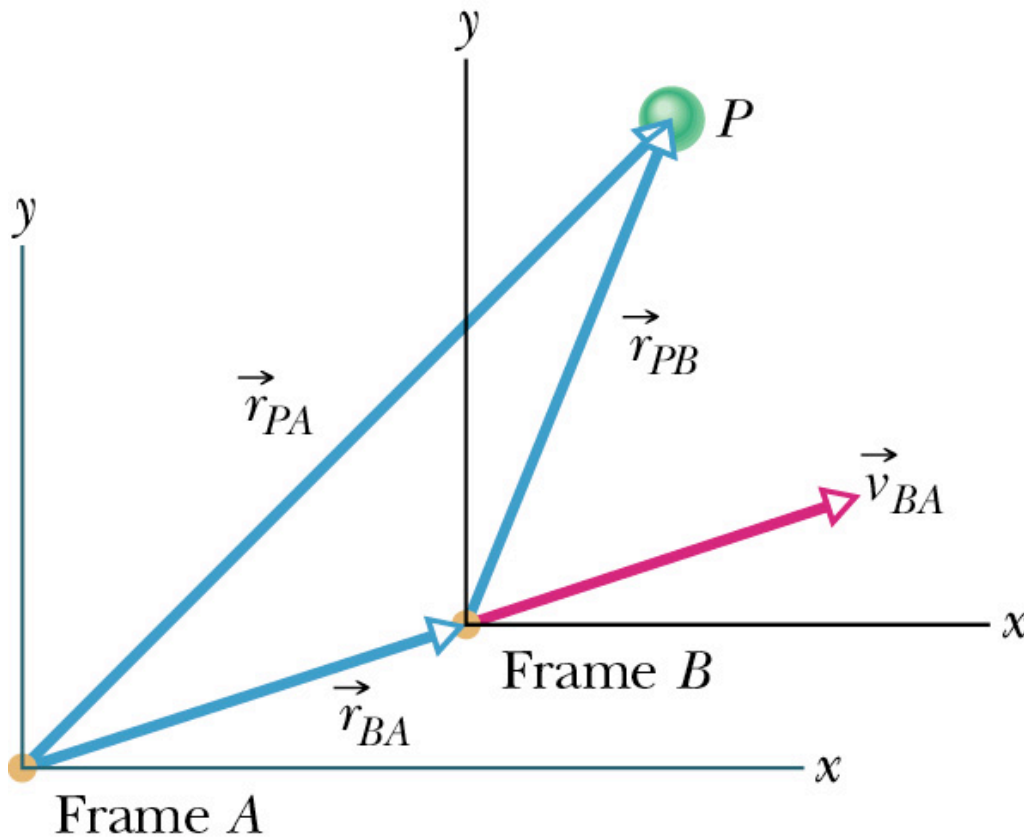
$$v_{PA} = v_{PB} + v_{BA}$$

(Special theory of relativity rejects this. We won't discuss it though)

$$a_{PA} = a_{PB}$$

$$\frac{dv_{BA}}{dt} = 0$$

Relative Motion in Two dimensions



We extend the discussion from the one dimensional case

$$\vec{r}_{PA} = \vec{r}_{PB} + \vec{r}_{BA}$$

$$\vec{v}_{PA} = \vec{v}_{PB} + \vec{v}_{BA}$$

(we assume a constant speed v_{BA})

$$\vec{a}_{PA} = \vec{a}_{PB}$$

Summary

Position Vector $\vec{r} = x\hat{i} + y\hat{j} + z\hat{k}$

Displacement Vector $\Delta\vec{r} = \vec{r}_2 - \vec{r}_1$

Projectile motion: equation of parabola

Uniform circular motion: $a = \frac{v^2}{r}$

Relative (uniform) motion: $\vec{a}_{PA} = \vec{a}_{PB}$